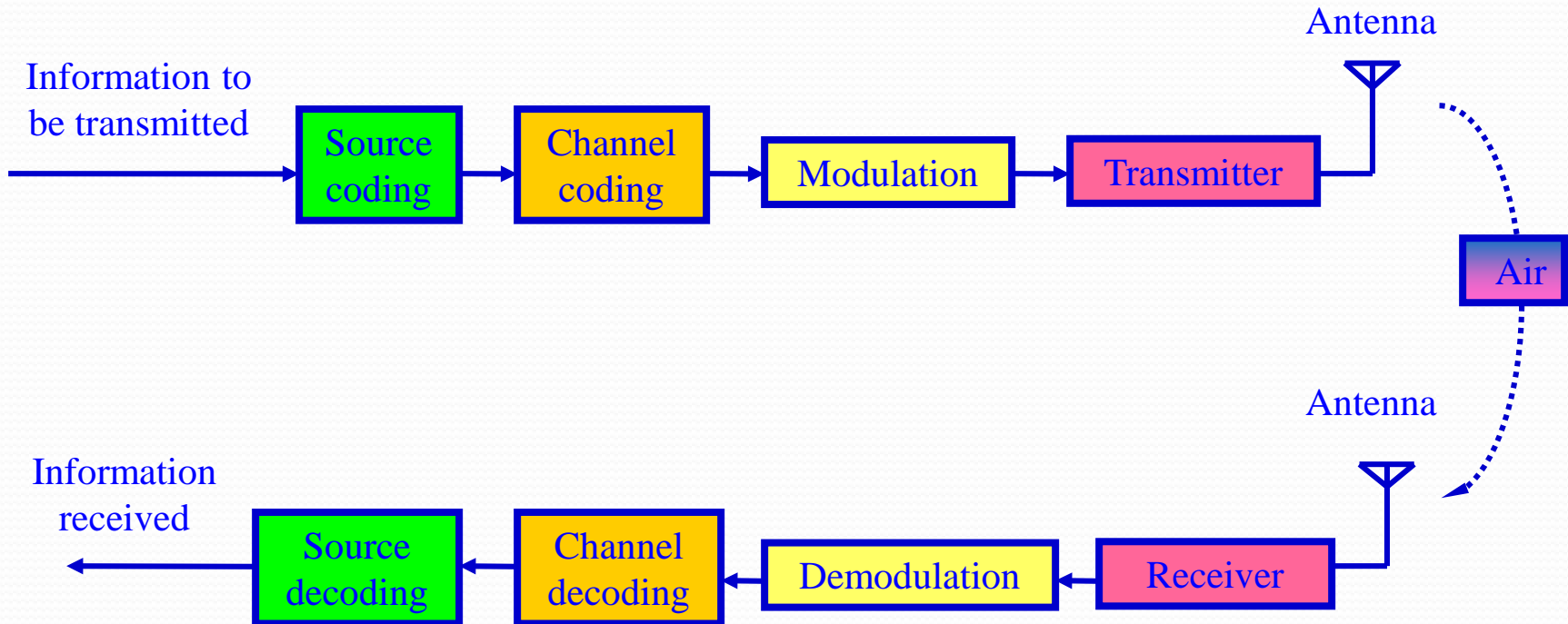


Chapter 4 Channel Coding and Error Control

Outline

- Introduction
- Block Codes
- Cyclic Codes
- CRC (Cyclic Redundancy Check)
- Convolutional Codes
- Interleaving
- Information Capacity Theorem
- Turbo Codes
- ARQ (Automatic Repeat Request)
 - Stop-and-wait ARQ
 - Go-back-N ARQ
 - Selective-repeat ARQ

Introduction



Forward Error Correction (FEC)

- The key idea of FEC is to transmit enough redundant data to allow receiver to recover from errors all by itself. No sender retransmission required
- A simple redundancy is to attach a parity bit
1010110
- The major categories of FEC codes are
 - Block codes
 - Cyclic codes
 - Reed-Solomon codes (Not covered here)
 - Convolutional codes, and
 - Turbo codes, etc.

Linear Block Codes

- Information is divided into blocks of length k
- r parity bits or check bits are added to each block (total length $n = k + r$)
- Code rate $R = k/n$
- Decoder looks for codeword closest to received vector (code vector + error vector)
- Tradeoffs between
 - Efficiency
 - Reliability
 - Encoding/Decoding complexity
- Modulo 2 Addition

$$\begin{array}{cccc}
 0 & 0 & 1 & 1 \\
 0 & 1 & 0 & 1 \\
 \hline
 0 & 1 & 1 & 10
 \end{array}$$

Linear Block Codes: Example

Example: Find linear block code encoder G if code generator polynomial $g(x) = 1 + x + x^3$ for a $(7, 4)$ code; n = Total number of bits = 7, k = Number of information bits = 4, r = Number of parity bits = $n - k = 3$

$$p_1 = \text{Re} \left[\frac{x^3}{x^3 + x + 1} \right] = 1 + x \rightarrow [110]$$

$$p_2 = \text{Re} \left[\frac{x^4}{x^3 + x + 1} \right] = x + x^2 \rightarrow [011]$$

$$p_3 = \text{Re} \left[\frac{x^5}{x^3 + x + 1} \right] = 1 + x + x^2 \rightarrow [111]$$

$$p_4 = \text{Re} \left[\frac{x^6}{x^3 + x + 1} \right] = 1 + x^2 \rightarrow [101]$$

Coefficients of $x^0 x^1 x^2$

$$G = \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 1 \end{array} \right] = [I | P]$$

I is the identity matrix
 P is the parity matrix

Linear Block Codes: Example

The Generator Polynomial can be used to determine the Generator Matrix **G** that allows determination of parity bits for a given data bits of **m** by multiplying as follows:

$$m.G = [1011] \begin{bmatrix} 1000110 \\ 0100011 \\ 0010111 \\ 0001101 \end{bmatrix} = [1011 | 100]$$

↑
↑
↑

 Data
 Data
Parity

Can be done for other combination of data bits, giving the code word **c**

Other combinations of **m** can be used to determine all other possible code words

Linear Block Codes

k - data and $r = n-k$ redundant bits

$$\left\{ \begin{array}{l} c_1 = m_1 \\ c_2 = m_2 \\ \dots \\ c_k = m_k \end{array} \right.$$

$$\left\{ \begin{array}{l} c_{k+1} = m_1 p_{1(k+1)} \oplus m_2 p_{2(k+1)} \oplus \dots \oplus m_k p_{k(k+1)} \\ \dots \\ c_n = m_1 p_{1n} \oplus m_2 p_{2n} \oplus \dots \oplus m_k p_{kn} \end{array} \right.$$

Linear Block Codes

- The uncoded k data bits be represented by the \mathbf{m} vector:

$$\mathbf{m} = (m_1, m_2, \dots, m_k)$$

The corresponding codeword be represented by the n -bit \mathbf{c} vector:

$$\mathbf{c} = (c_1, c_2, \dots, c_k, c_{k+1}, \dots, c_{n-1}, c_n)$$

- Each parity bit consists of weighted modulo 2 sum of the data bits represented by symbol for Exclusive OR or modulo 2 addition

Linear Block Codes

- Linear Block Code

The block length C of the Linear Block Code is

$$\mathbf{C} = \mathbf{mG}$$

where m is the information codeword block length, \mathbf{G} is the generator matrix.

$$\mathbf{G} = [\mathbf{I}_k \mid \mathbf{P}]_{k \times n}$$

where $P_i = \text{Remainder of } [x^{n-k+i-1}/g(x)]$ for $i=1, 2, \dots, k$, and \mathbf{I} is unit or identity matrix.

- At the receiving end, parity check matrix can be given as:

$$\mathbf{H} = [\mathbf{P}^T \mid \mathbf{I}_{n-k}], \quad \text{where } \mathbf{P}^T \text{ is the transpose of the matrix } \mathbf{p}.$$

Linear Block Codes

Example: Find linear block code encoder \mathbf{G} if code generator polynomial $g(x)$ with k data bits, and r parity bits = $n - k$

$$\therefore \mathbf{G} = [\mathbf{I} \mid \mathbf{P}] = \begin{bmatrix} 1 & 0 & \dots & 0 & P^1 \\ 0 & 1 & \dots & 0 & P^2 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 1 & P^k \end{bmatrix}$$

where

$$P^i = \text{Remainder of } \left[\frac{x^{n-k+i-1}}{g(x)} \right], \text{ for } i = 1, 2, \dots, k$$

Linear Block Codes

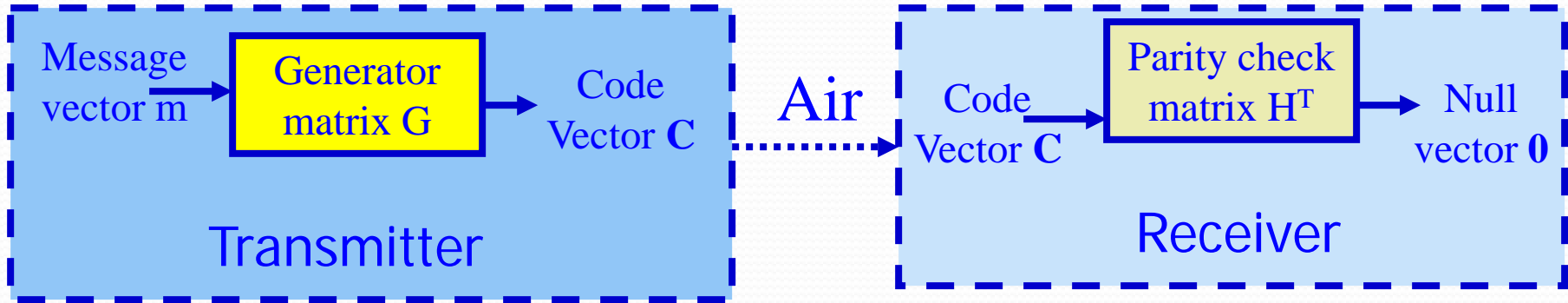
Example: The parity matrix \mathbf{P} (k by $n-k$ matrix) is given by:

$$\mathbf{P} = \begin{bmatrix} p_{11} p_{12} \cdots p_{1(n-k)} \\ p_{21} p_{22} \cdots p_{2(n-k)} \\ \dots \dots \dots \\ p_{k1} p_{k1} \cdots p_{k(n-k)} \end{bmatrix} = \begin{bmatrix} P^1 \\ P^2 \\ \dots \\ P^k \end{bmatrix}$$

where

$$P^i = \text{Remainder of } \left[\frac{x^{n-k+i-1}}{g(x)} \right], \text{ for } i = 1, 2, \dots, k$$

Block Codes: Linear Block Codes



Operations of the generator matrix and the parity check matrix

- Consider a (7, 4) linear block code, given by G as

$$G = \begin{bmatrix} 1000 & | & 111 \\ 0100 & | & 110 \\ 0010 & | & 101 \\ 0001 & | & 011 \end{bmatrix} \quad H^T = \begin{bmatrix} P \\ I_{n-k} \end{bmatrix} = \begin{bmatrix} 1110 & | & 100 \\ 1101 & | & 010 \\ 1011 & | & 001 \end{bmatrix}^T$$

For convenience, the code vector is expressed as

$$\mathbf{c} = \left[\mathbf{m} \mid \mathbf{c}_p \right] \quad \text{Where } \mathbf{c}_p = \mathbf{mP} \text{ is an } (n-k)\text{-bit parity check vector}$$

Block Codes: Linear Block Codes

Define matrix \mathbf{H}^T as
$$\mathbf{H}^T = \begin{bmatrix} \mathbf{P} \\ \mathbf{I}_{n-k} \end{bmatrix}$$

Received code vector $\mathbf{x} = \mathbf{c} \oplus \mathbf{e}$, here \mathbf{e} is an error vector, the matrix \mathbf{H}^T has the property

$$\begin{aligned} \mathbf{cH}^T &= \left[\mathbf{m} \mid \mathbf{c}_p \right] \begin{bmatrix} \mathbf{P} \\ \mathbf{I}_{n-k} \end{bmatrix} \\ &= \mathbf{mP} \oplus \mathbf{c}_p = \mathbf{c}_p \oplus \mathbf{c}_p = \mathbf{0} \end{aligned}$$

The transpose of matrix \mathbf{H}^T is

$$\mathbf{H} = \left[\mathbf{P}^T \mid \mathbf{I}_{n-k} \right] \quad \text{Where } \mathbf{I}_{n-k} \text{ is a } n-k \text{ by } n-k \text{ unit matrix} \\ \text{and } \mathbf{P}^T \text{ is the transpose of parity matrix } \mathbf{P}.$$

\mathbf{H} is called parity check matrix.

Compute syndrome as
$$\mathbf{s} = \mathbf{xH}^T = (\mathbf{c} \oplus \mathbf{e}) \times \mathbf{H}^T = \mathbf{cH}^T \oplus \mathbf{eH}^T = \mathbf{eH}^T$$

Linear Block Codes

If \mathbf{S} is $\mathbf{0}$ then message is correct else there are errors in it, from common known error patterns the correct message can be decoded.

- For the (7, 4) linear block code, given by \mathbf{G} as

$$\mathbf{G} = \begin{bmatrix} 1000 & | & 111 \\ 0100 & | & 110 \\ 0010 & | & 101 \\ 0001 & | & 011 \end{bmatrix} \quad \mathbf{H} = \begin{bmatrix} 1110 & | & 100 \\ 1101 & | & 010 \\ 1011 & | & 001 \end{bmatrix}$$

- For $\mathbf{m} = [1 \ 0 \ 1 \ 1]$ and $\mathbf{c} = \mathbf{mG} = [1 \ 0 \ 1 \ 1 \ | \ 0 \ 0 \ 1]$
If there is no error, the received vector $\mathbf{x} = \mathbf{c}$, and
 $\mathbf{s} = \mathbf{cH}^T = [0, 0, 0]$

Linear Block Codes

Let \mathbf{c} suffer an error such that the received vector

$$\begin{aligned} \mathbf{x} &= \mathbf{c} + \mathbf{e} \\ &= [1\ 0\ 1\ 1\ 0\ 0\ 1] + [0\ 0\ 1\ 0\ 0\ 0\ 0] \\ &= [1\ 0\ 0\ 1\ 0\ 0\ 1] \end{aligned}$$

Then,

$$\text{Syndrome } \mathbf{s} = \mathbf{xH}^T$$

$$= [1\ 0\ 0\ 1 \mid 0\ 0\ 1] \begin{bmatrix} 111 \\ 110 \\ 101 \\ 011 \\ - \\ - \\ 100 \\ 010 \\ 001 \end{bmatrix} = [1\ 0\ 1] = (\mathbf{eH}^T)$$

This indicates error position, giving the corrected vector as [1011001]

Cyclic Codes

It is a block code which uses a shift register to perform encoding and decoding the code word with n bits is expressed as:

$$c(x) = c_1x^{n-1} + c_2x^{n-2} + \dots + c_n$$

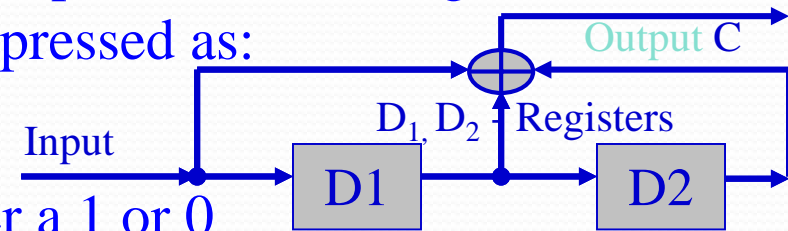
where each coefficient c_i ($i=1,2,\dots,n$) is either a 1 or 0

The codeword can be expressed by the data polynomial $m(x)$ and the check polynomial $c_p(x)$ as

$$c(x) = m(x) x^{n-k} + c_p(x)$$

where $c_p(x)$ = remainder from dividing $m(x) x^{n-k}$ by generator $g(x)$
if the received signal is $c(x) + e(x)$ where $e(x)$ is the error

To check if received signal is error free, the remainder from dividing $c(x) + e(x)$ by $g(x)$ is obtained (syndrome). If this is 0 then the received signal is considered error free else error pattern is detected from known error syndromes



Cyclic Code: Example

Example: Find the code words $c(x)$ if $m(x) = x^2 + x + 1$ and $g(x) = x^3 + x + 1$ for (7, 4) cyclic code

We have $n = \text{total number of bits} = 7$, $k = \text{number of information bits} = 4$,
 $r = \text{number of parity bits} = n - k = 3$

$$\begin{aligned} \therefore c_p(x) &= \text{rem} \left[\frac{m(x)x^{n-k}}{g(x)} \right] \\ &= \text{rem} \left[\frac{x^5 + x^4 + x^3}{x^3 + x + 1} \right] = x \end{aligned}$$

Then,

$$c(x) = m(x)x^{n-k} + c_p(x) = x + x^3 + x^4 + x^5$$

Cyclic Redundancy Check (CRC)

- Cyclic Redundancy Code (CRC) is an error-checking code
- The transmitter appends an extra n -bit sequence to every frame called Frame Check Sequence (FCS). The FCS holds redundant information about the frame that helps the receivers detect errors in the frame
- CRC is based on polynomial manipulation using modulo arithmetic. Blocks of input bit as coefficient-sets for polynomials is called message polynomial. Polynomial with constant coefficients is called the generator polynomial

Cyclic Redundancy Check (CRC)

- Generator polynomial is divided into the message polynomial, giving quotient and remainder, the coefficients of the remainder form the bits of final CRC
- **Define:**
 - Q – The original frame (k bits) to be transmitted
 - F – The resulting frame check sequence (FCS) of $n-k$ bits to be added to Q (usually $n = 8, 16, 32$)
 - J – The cascading of Q and F
 - P – The predefined CRC generating polynomial

The main idea in CRC algorithm is that the FCS is generated so that J should be exactly divisible by P

Cyclic Redundancy Check (CRC)

- The CRC creation process is defined as follows:
 - Get the block of raw message
 - Left shift the raw message by n bits and then divide it by p
 - Get the remainder R as FCS
 - Append the R to the raw message. The result J is the frame to be transmitted $J=Q.x^{n-k}+F$
 - J should be exactly divisible by P
- Dividing $Q.x^{n-k}$ by P gives $Q.x^{n-k}/P=Q+R/P$
 - Where R is the remainder
 - $J=Q.x^{n-k}+R$. This value of J should yield a zero remainder for J/P

Common CRC Codes

Code-parity check bits	Generator polynomial $g(x)$
CRC-12	$x^{12} + x^{11} + x^3 + x^2 + x + 1$
CRC-16	$x^{16} + x^{15} + x^2 + 1$
CRC-CCITT	$x^{16} + x^{12} + x^5 + 1$
CRC-32	$x^{32} + x^{26} + x^{23} + x^{22} + x^{16}$ $+ x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$

Common CRC Codes

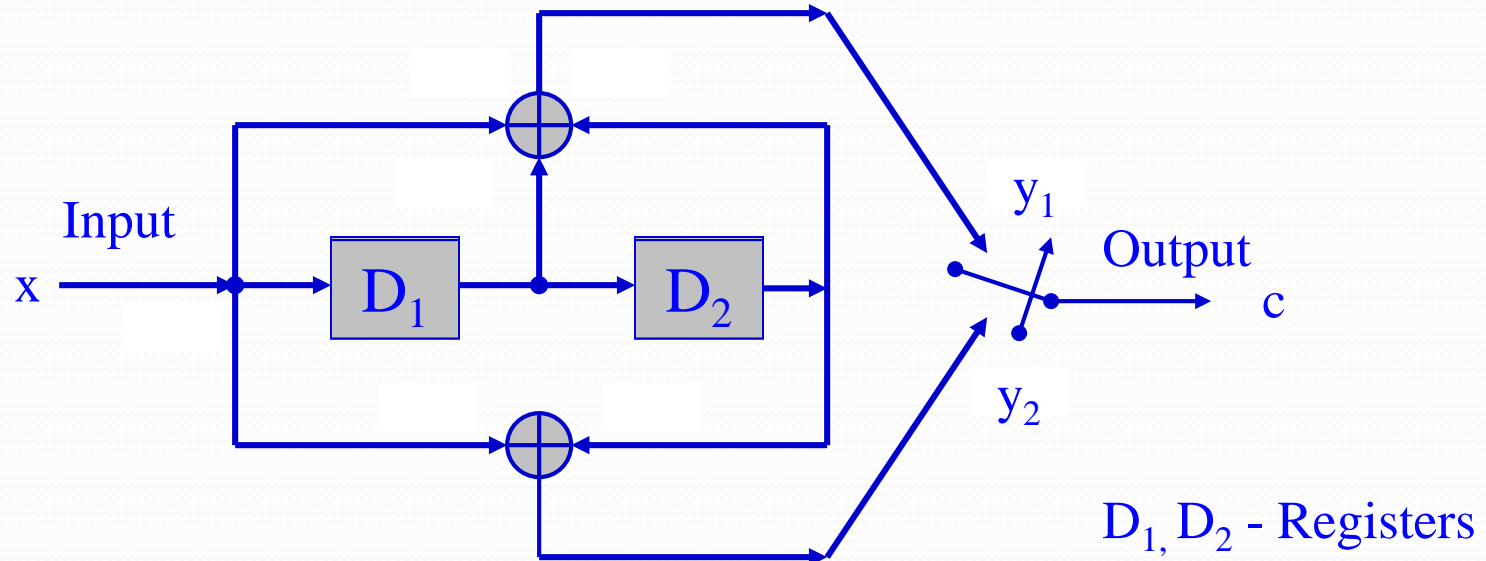
Code	Generator polynomial $g(x)$	Parity check bits
CRC-12	$1+x+x^2+x^3+x^{11}+x^{12}$	12
CRC-16	$1+x^2+x^{15}+x^{16}$	16
CRC-CCITT	$1+x^5+x^{15}+x^{16}$	16

Convolutional Codes

- Most widely used channel code
- Encoding of information stream rather than information blocks
- Decoding is mostly performed by the Viterbi Algorithm (not covered here)

- The constraint length K for a convolution code is defined as $K=M+1$ where M is the maximum number of stages in any shift register
- The code rate r is defined as $r = k/n$ where k is the number of parallel information bits and n is the the number of parallel output encoded bits at one time interval
- A convolution code encoder with $n=2$ and $k=1$ or code rate $r=1/2$ is shown next

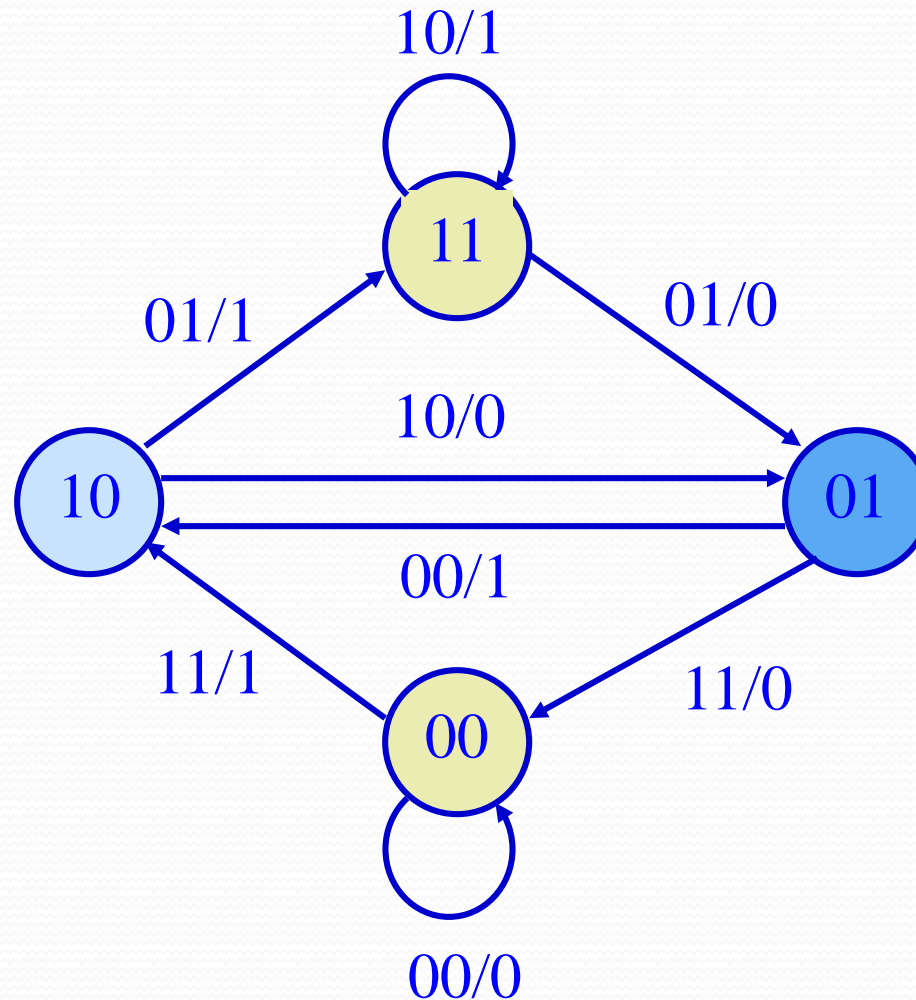
Convolutional Codes: $(n=2, k=1, M=2)$ Encoder



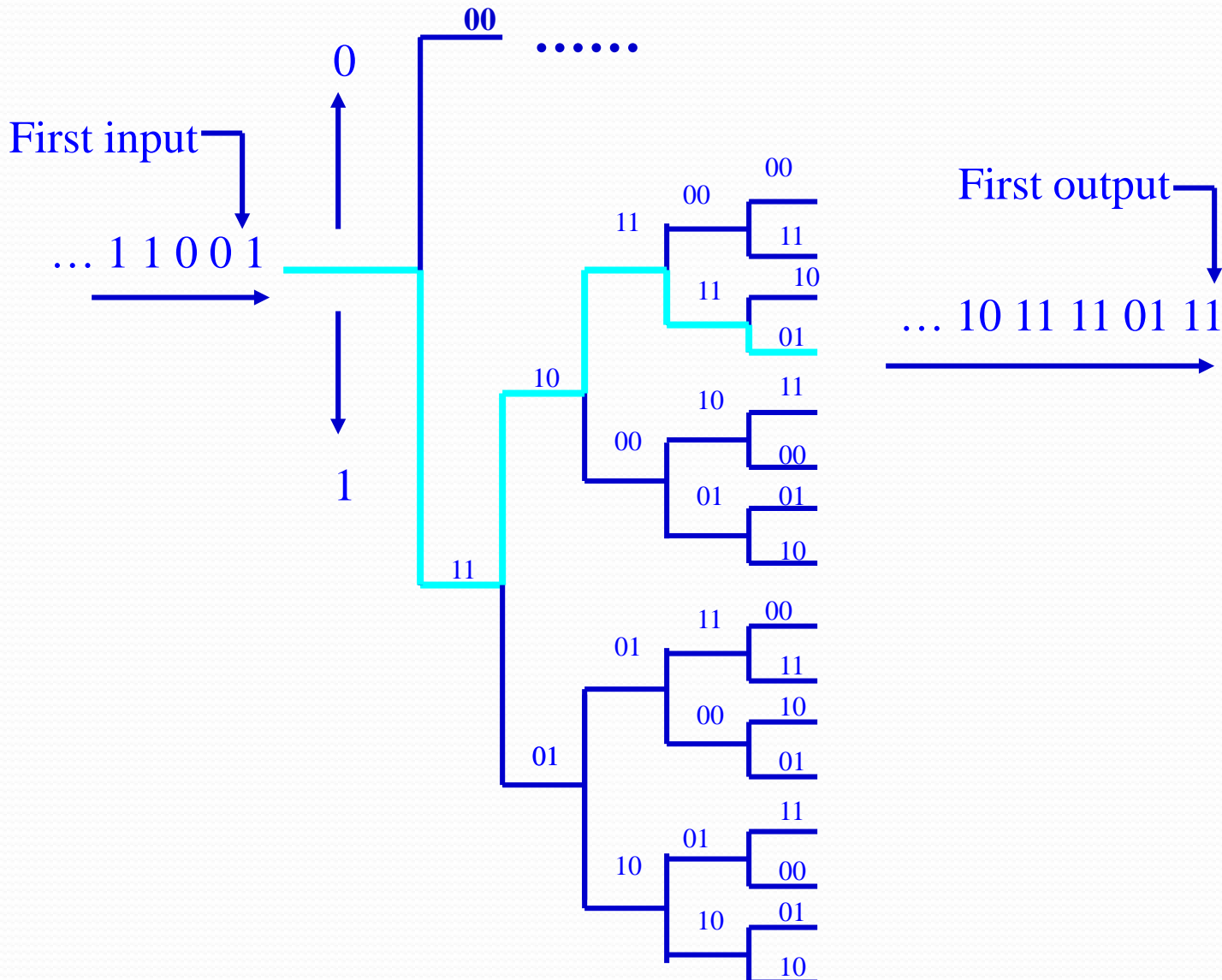
Input x :	1	1	1	0	0	0	...
Output $y_1 y_2$:	11	01	10	01	11	00	...

Input x :	1	0	1	0	0	0	...
Output $y_1 y_2$:	11	10	00	10	11	00	...

State Diagram

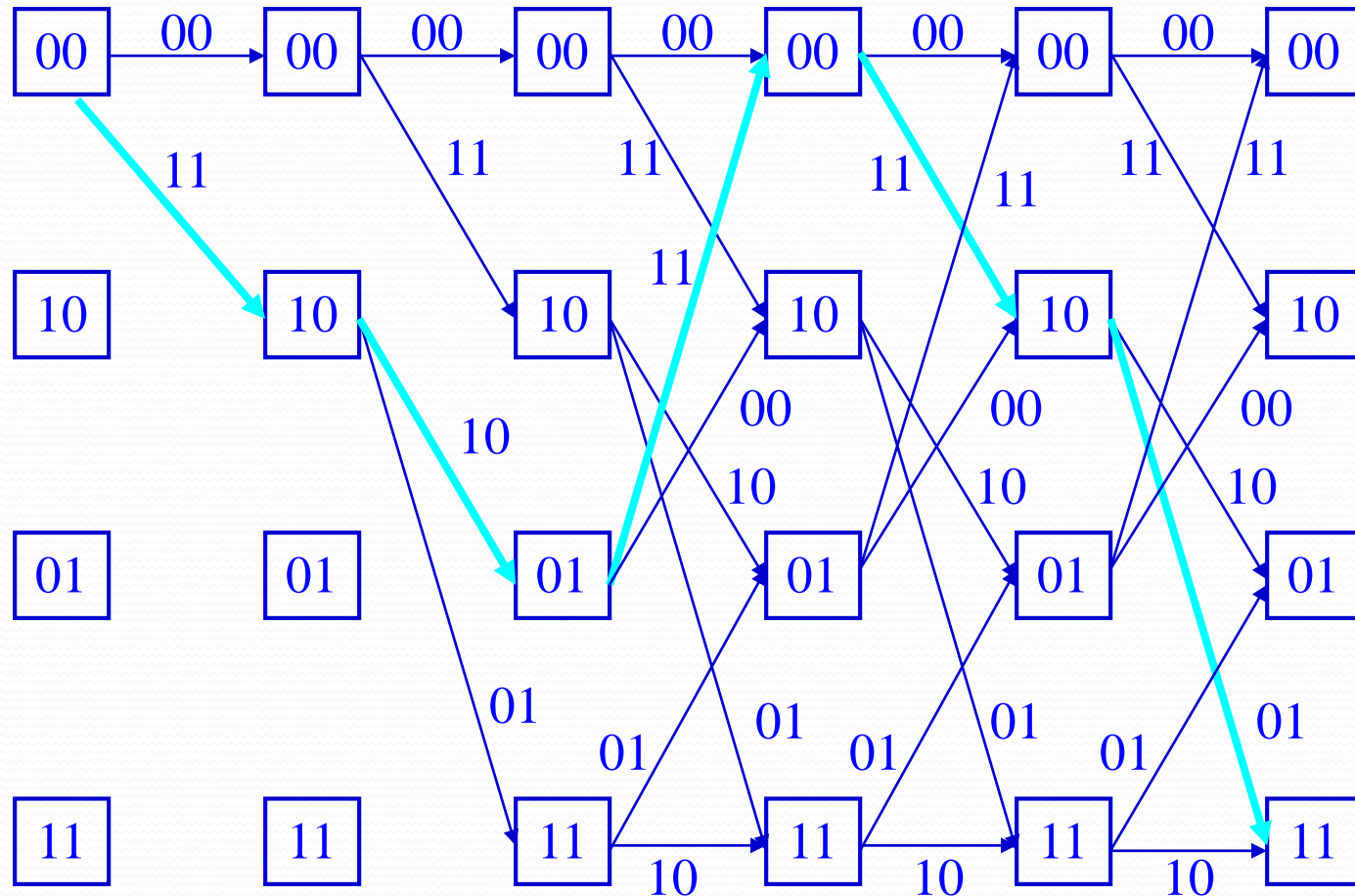


Tree Diagram

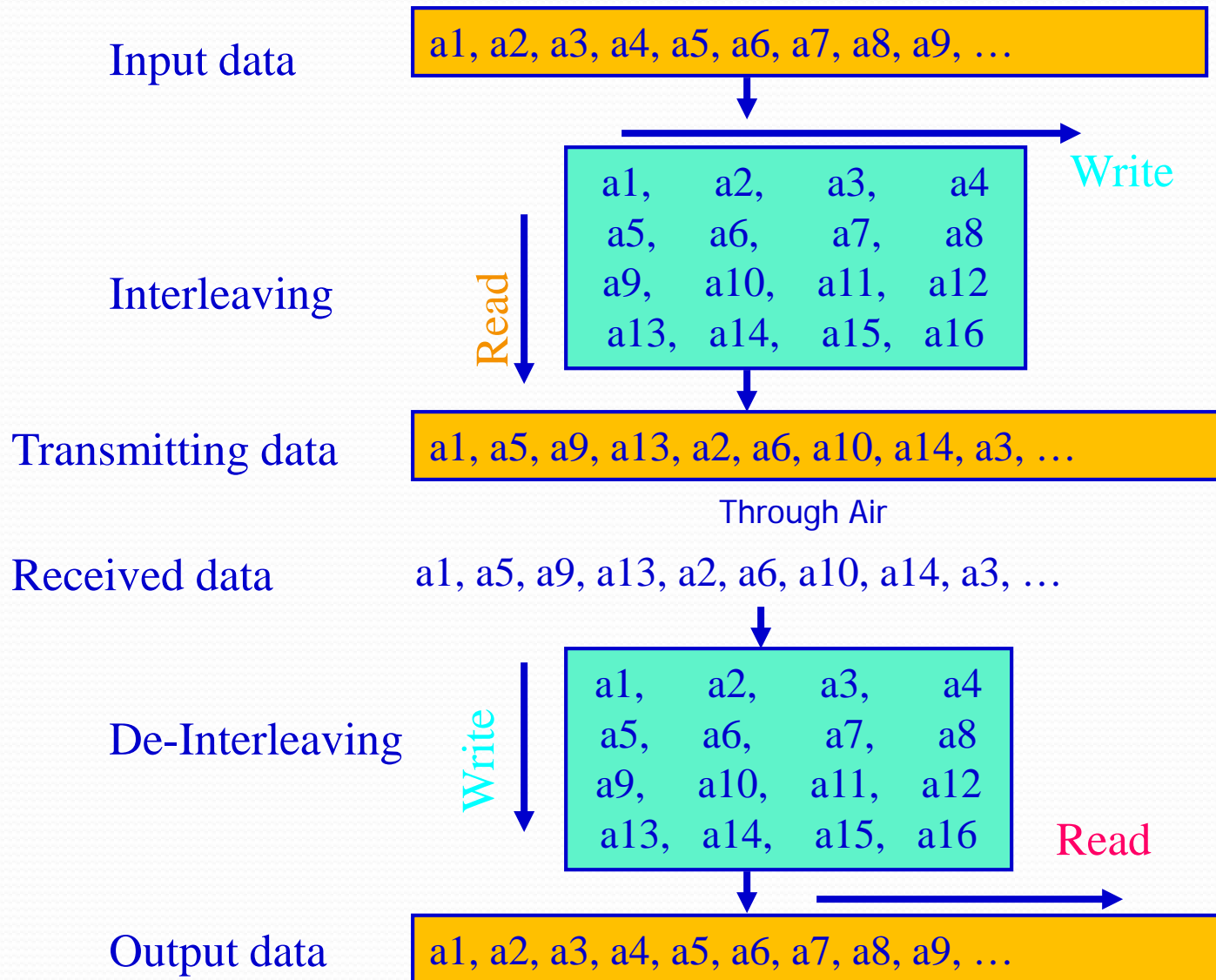


Trellis

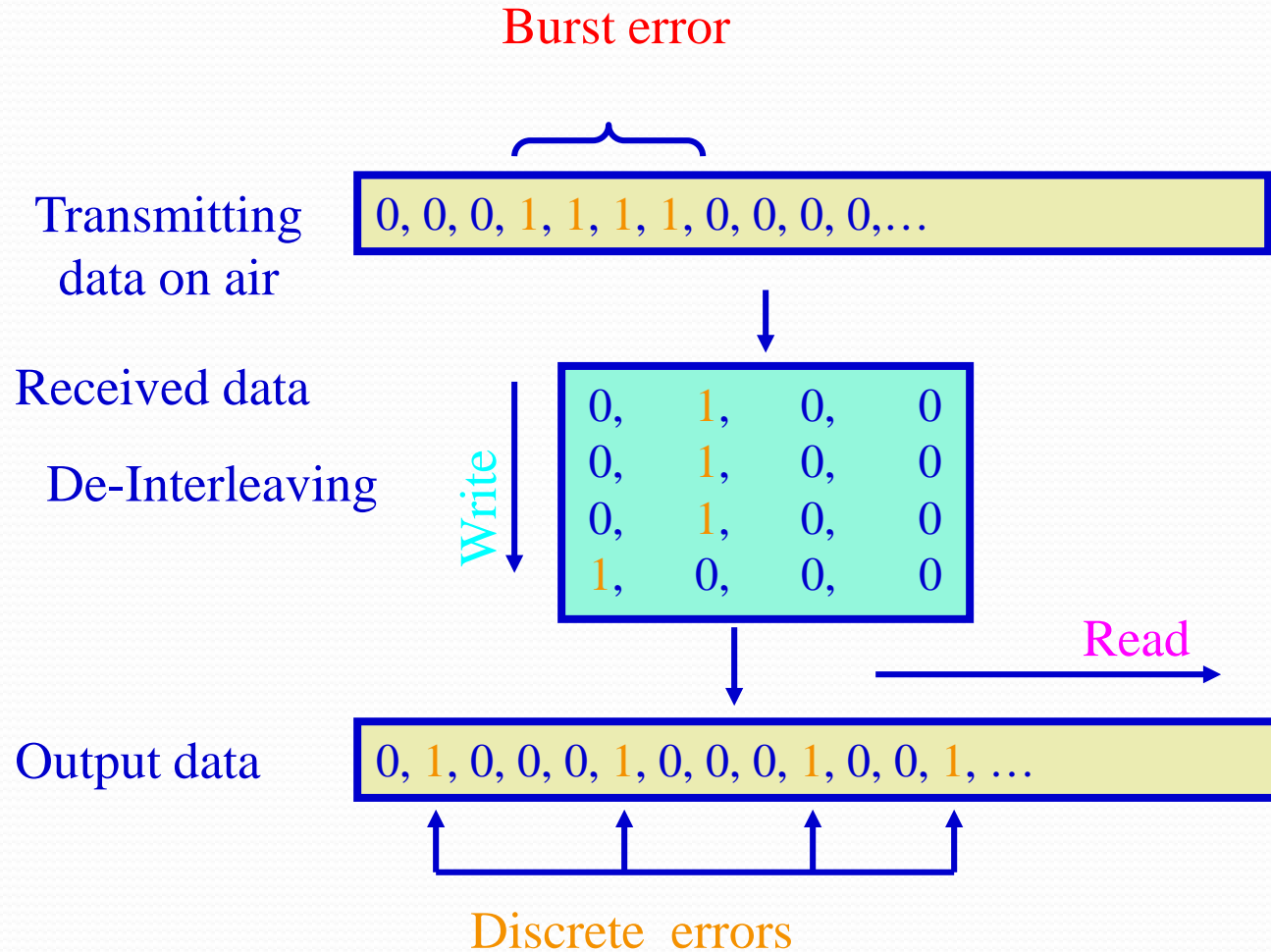
... 11 00 1



Interleaving



Interleaving (Example)



Information Capacity Theorem (Shannon Limit)

- The information capacity (or channel capacity) C of a continuous channel with bandwidth B Hertz can be perturbed by additive Gaussian white noise of power spectral density $N_0/2$, provided bandwidth B satisfies

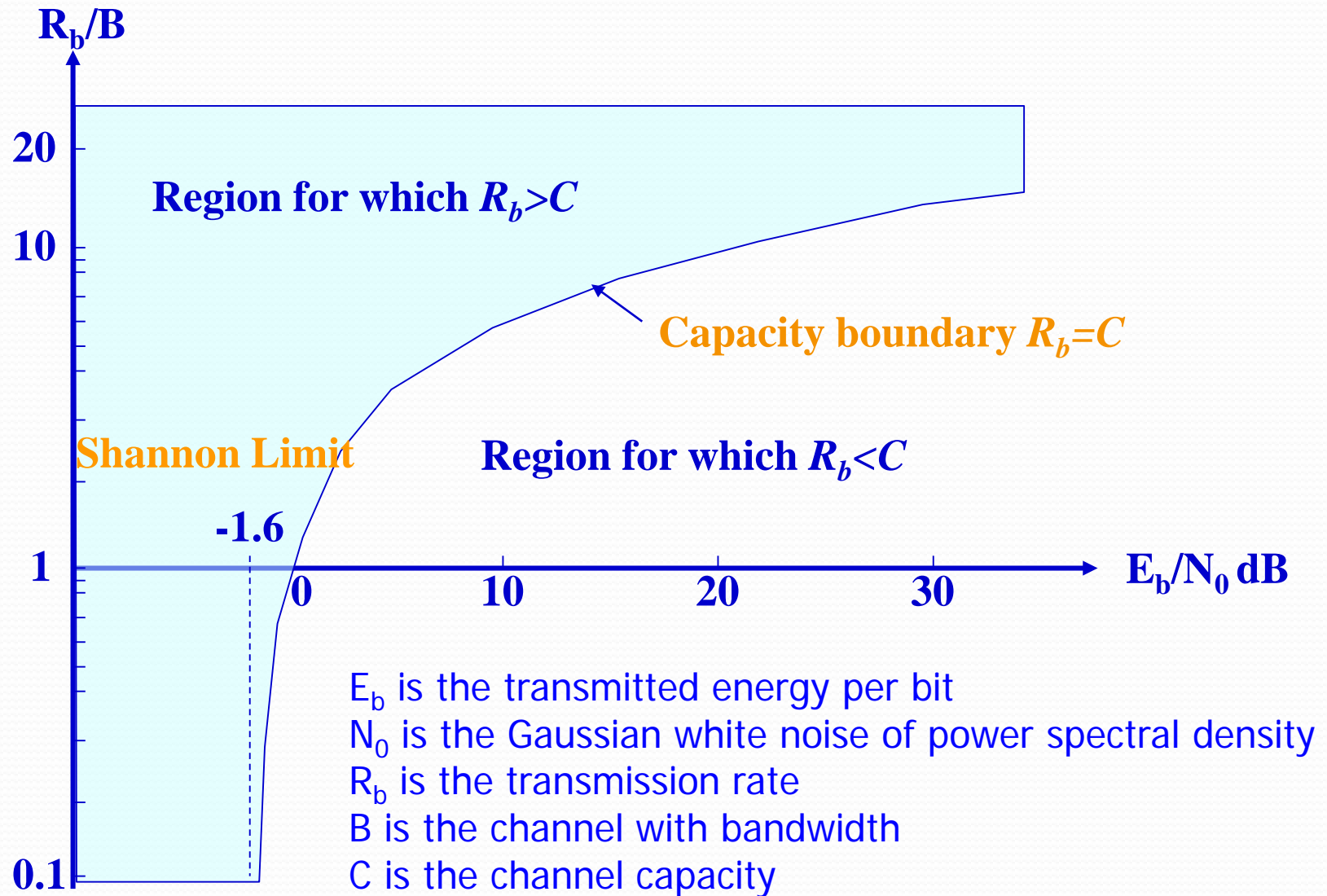
$$C = B \log_2 \left(1 + \frac{P}{N_0 B} \right) \text{ bits / second}$$

where P is the average transmitted power $P = E_b R_b$
(for an ideal system, $R_b = C$)

E_b is the transmitted energy per bit

R_b is transmission rate

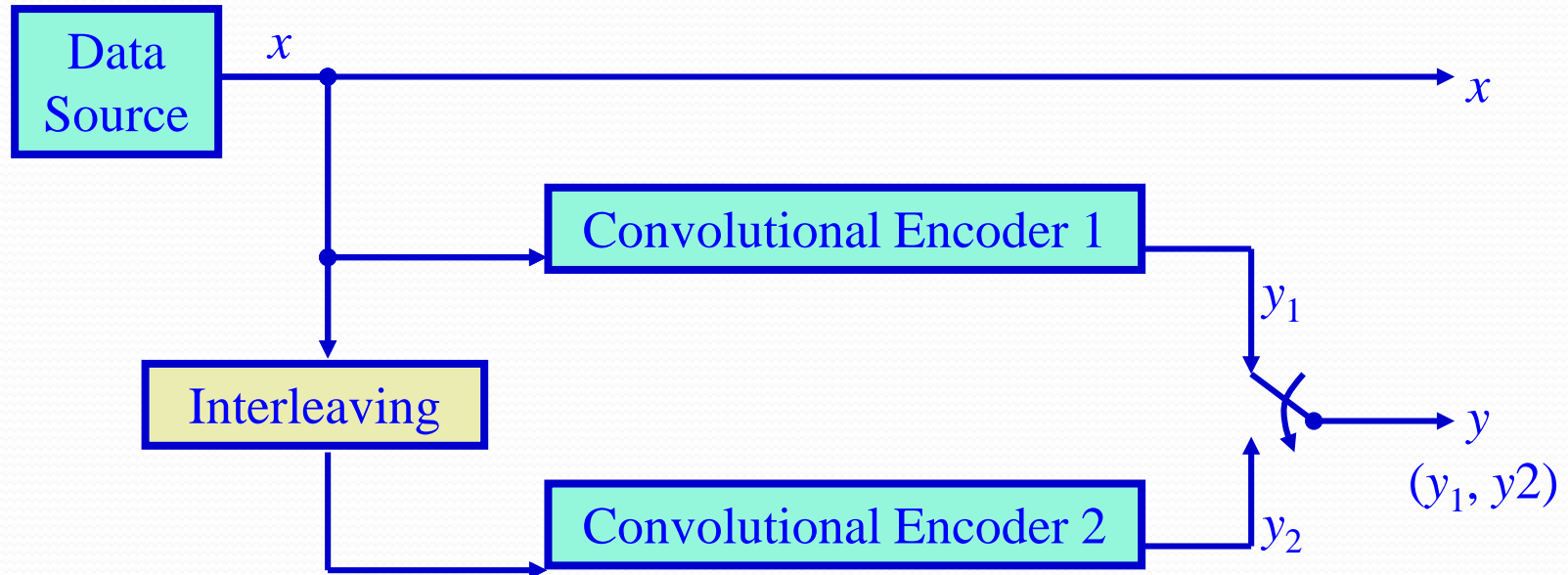
Shannon Limit



Turbo Codes

- A brief historic of turbo codes:
The turbo code concept was first introduced by C. Berrou in 1993. Today, Turbo Codes are considered as the most efficient coding schemes for FEC
- Scheme with known components (simple convolutional or block codes, interleaver, soft-decision decoder, etc.)
- Performance close to the Shannon Limit ($E_b/N_0 = -1.6$ db if $R_b \rightarrow 0$) at modest complexity!
- Turbo codes have been proposed for low-power applications such as deep-space and satellite communications, as well as for interference limited applications such as third generation cellular, personal communication services, ad hoc and sensor networks

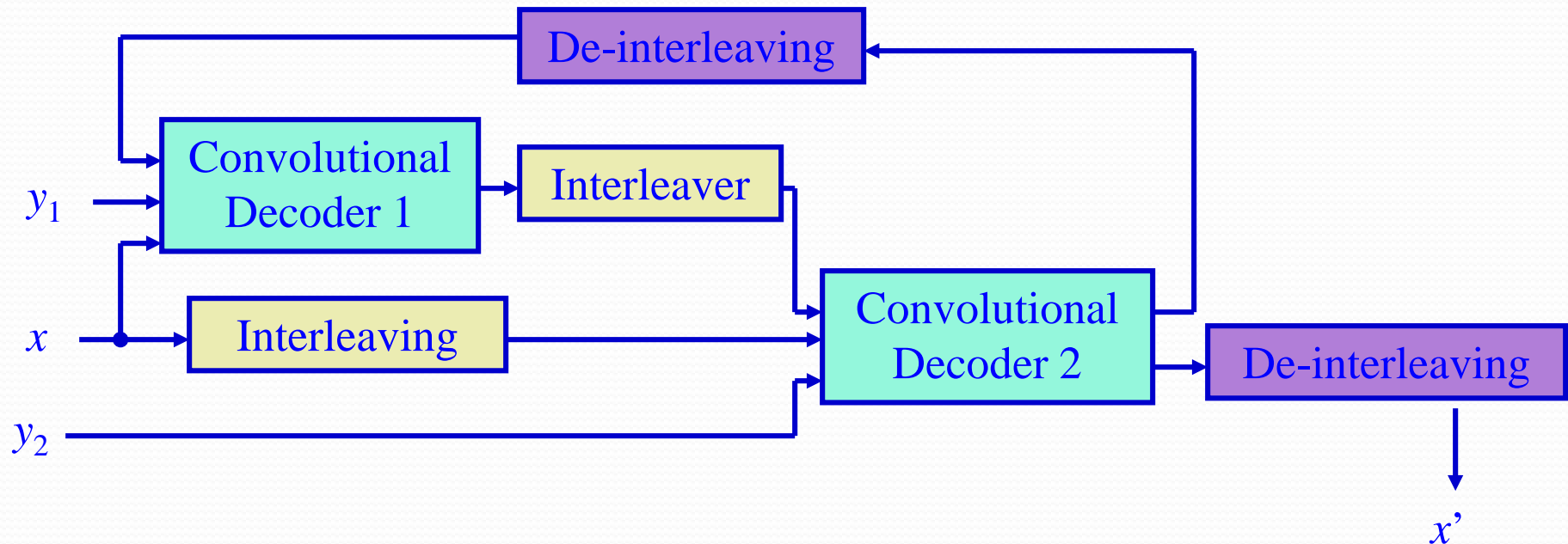
Turbo Codes: Encoder



x : Information

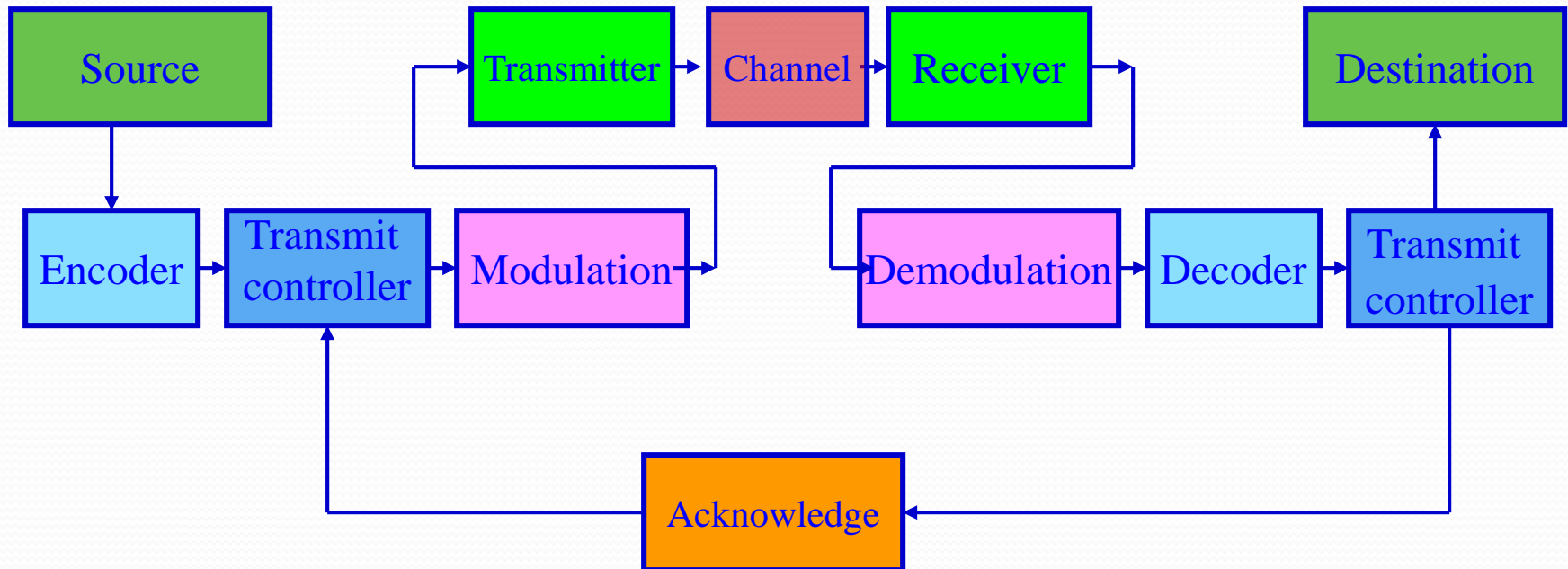
y_i : Redundancy Information

Turbo Codes: Decoder

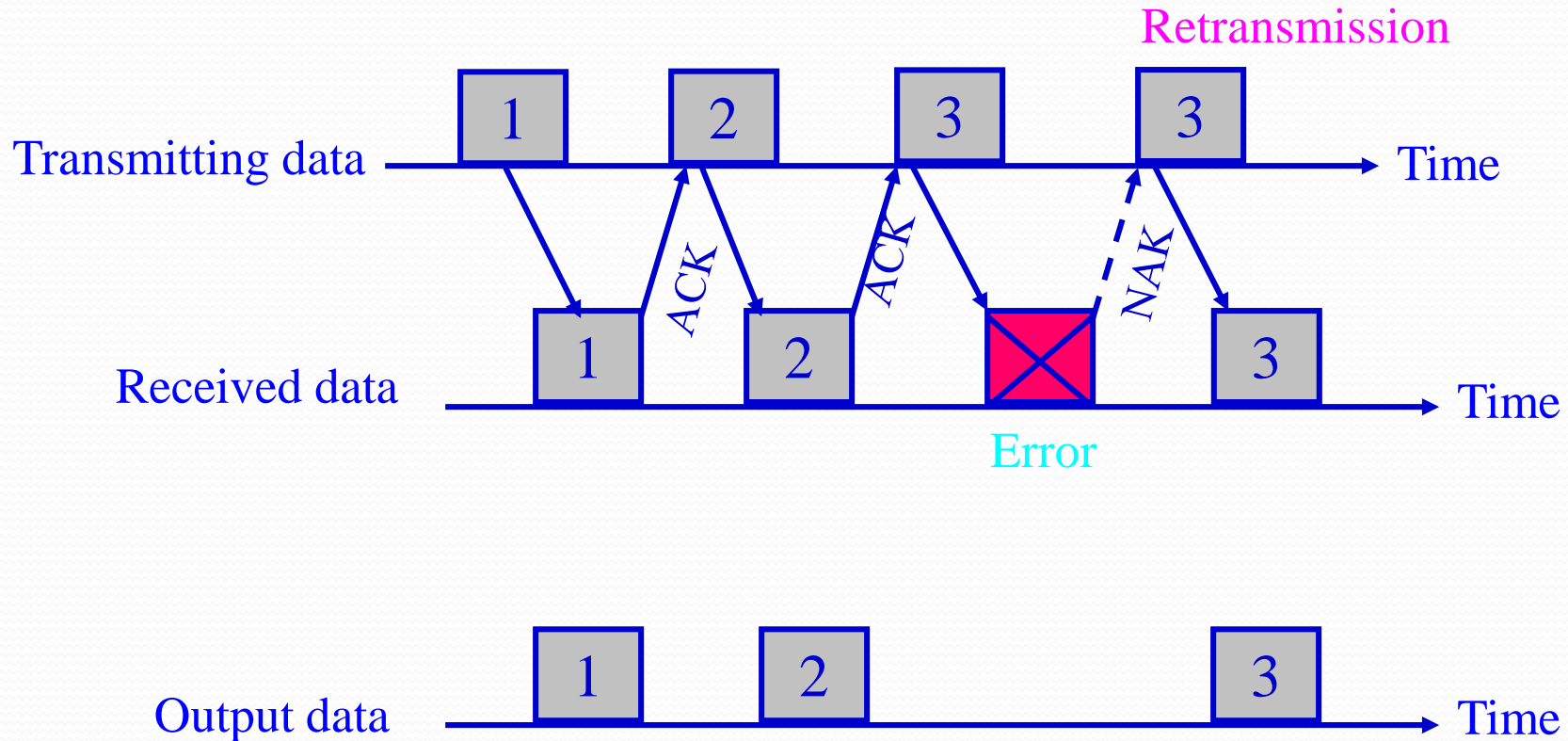


x' : Decoded Information

Automatic Repeat Request (ARQ)



Stop-And-Wait ARQ (SAW ARQ)



ACK: Acknowledge

NAK: Negative ACK

Stop-And-Wait ARO (SAW ARO)

Given n = number of bits in a block, k = number of information bits in a block, D = round trip delay, R_b = bit rate, P_b = BER of the channel, and

$$P_{ACK} \approx (1 - P_b)^n$$

Throughput:

$$S_{SAW} = (1/T_{SAW}) \cdot (k/n) = [(1 - P_b)^n / (1 + D \cdot R_b/n)] \cdot (k/n)$$

where T_{SAW} is the average transmission time in terms of a block duration

$$T_{SAW} = (1 + D \cdot R_b/n) \cdot P_{ACK} + 2 (1 + D \cdot R_b/n) P_{ACK} (1 - P_{ACK})$$

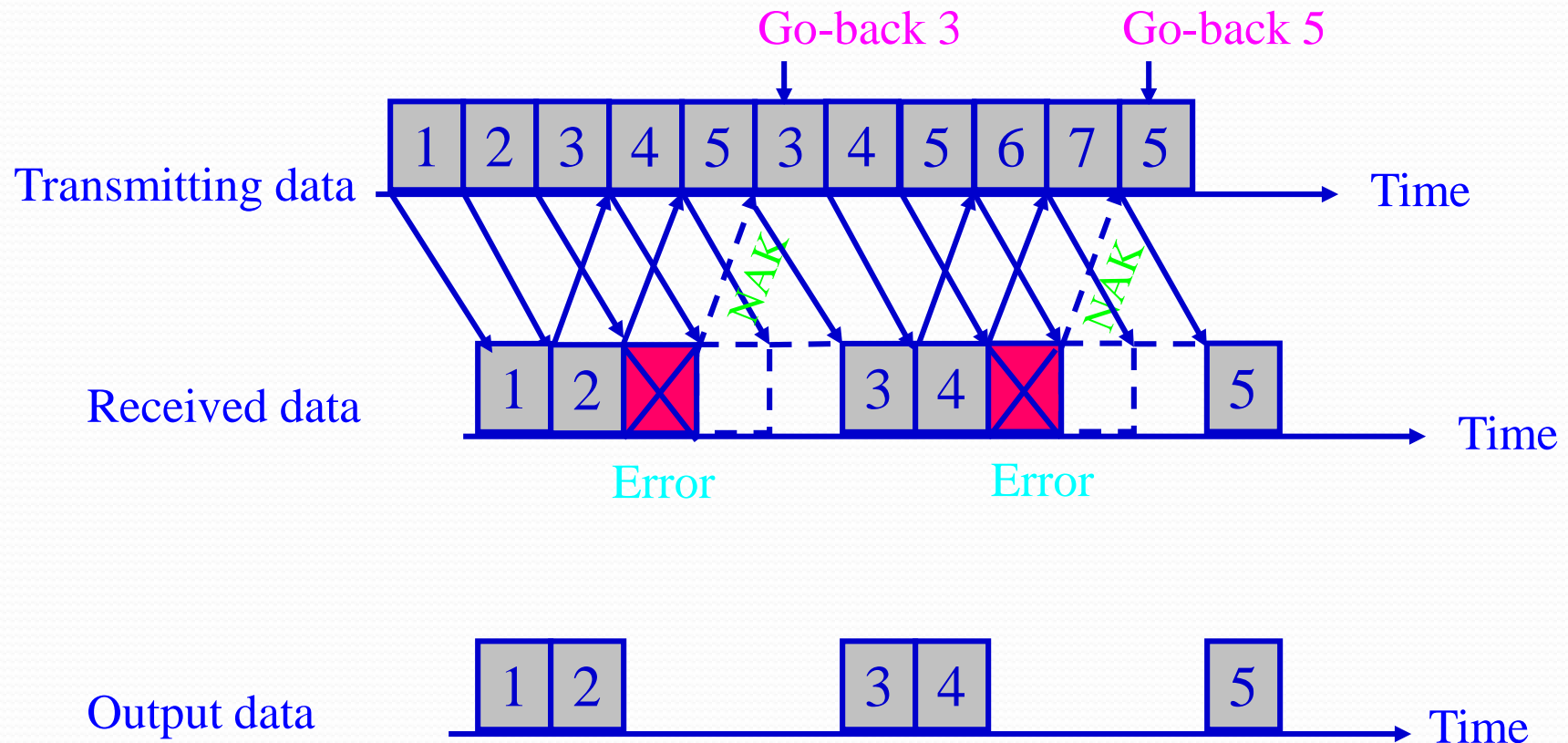
$$+ 3 (1 + D \cdot R_b/n) P_{ACK} (1 - P_{ACK})^2 + \dots$$

$$= (1 + D \cdot R_b/n) P_{ACK} \sum_{i=1}^{\infty} i (1 - P_{ACK})^{i-1}$$

$$= (1 + D \cdot R_b/n) P_{ACK} / [1 - (1 - P_{ACK})]^2$$

$$= (1 + D \cdot R_b/n) / P_{ACK}$$

Go-Back-N ARQ (GBN ARQ)



Go-Back-N ARQ (GBN ARQ)

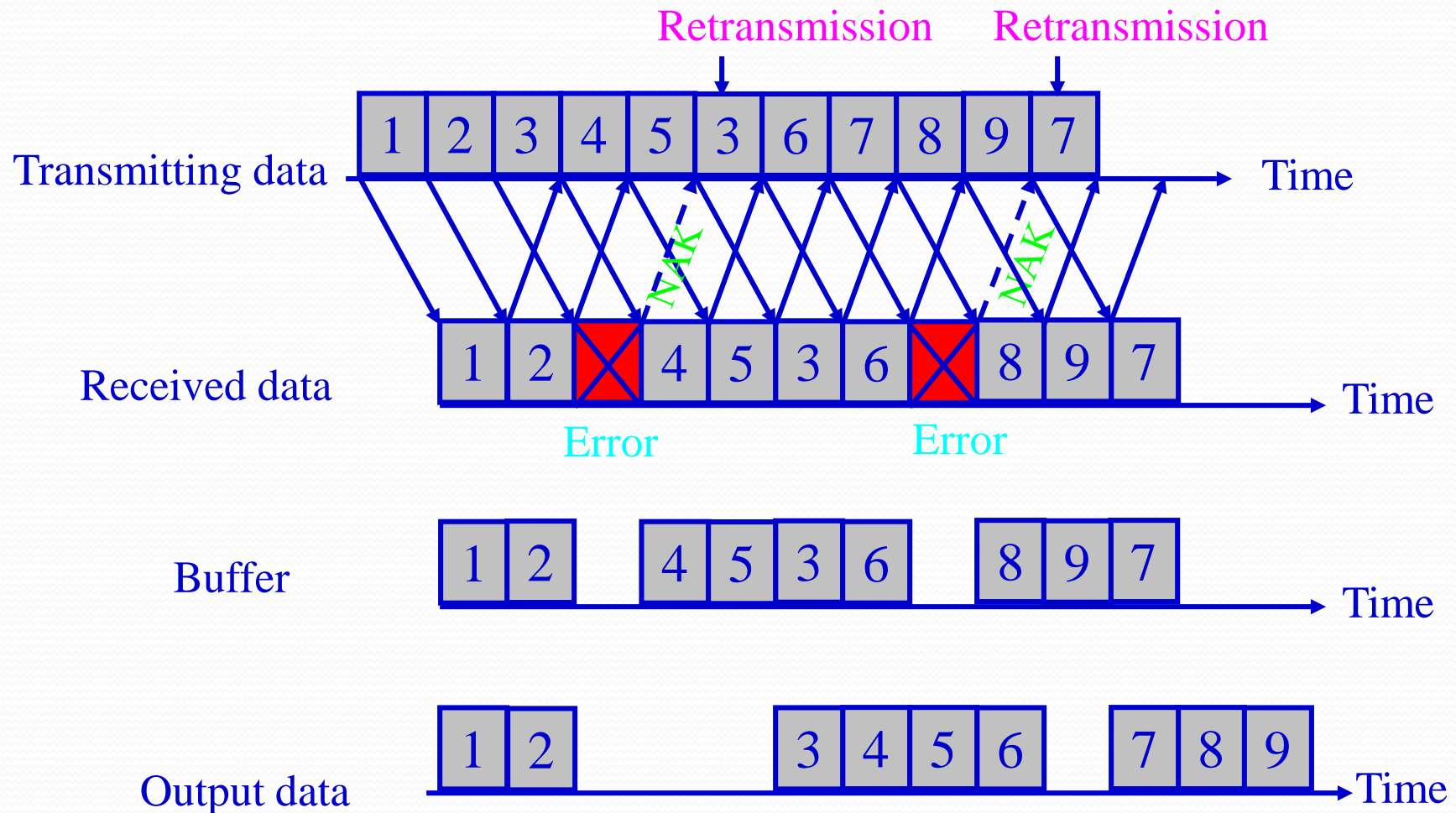
Throughput

$$\begin{aligned}
 S_{\text{GBN}} &= (1/T_{\text{GBN}}) (k/n) \\
 &= [(1 - P_b)^n / ((1 - P_b)^n + N (1 - (1 - P_b)^n))] (k/n)
 \end{aligned}$$

where

$$\begin{aligned}
 T_{\text{GBN}} &= 1 \cdot P_{\text{ACK}} + (N+1) \cdot P_{\text{ACK}} \cdot (1 - P_{\text{ACK}}) + 2 \cdot (N+1) \cdot P_{\text{ACK}} \cdot \\
 &\quad (1 - P_{\text{ACK}})^2 + \dots \\
 &= P_{\text{ACK}} + P_{\text{ACK}} [(1 - P_{\text{ACK}}) + (1 - P_{\text{ACK}})^2 + (1 - P_{\text{ACK}})^3 + \dots] + \\
 &\quad P_{\text{ACK}} [N (1 - P_{\text{ACK}}) + 2 N (1 - P_{\text{ACK}})^2 + 3 N (1 - P_{\text{ACK}})^3 + \dots] \\
 &= P_{\text{ACK}} + P_{\text{ACK}} [(1 - P_{\text{ACK}}) / \{1 - (1 - P_{\text{ACK}})\} + N (1 - P_{\text{ACK}}) / \{1 - (1 - P_{\text{ACK}})\}^2] \\
 &= 1 + N(1 - P_{\text{ACK}}) / P_{\text{ACK}} \approx 1 + (N [1 - (1 - P_b)^n]) / (1 - P_b)^n
 \end{aligned}$$

Selective-Repeat ARQ (SR ARQ)



Selective-Repeat ARQ (SR ARQ)

Throughput

$$S_{\text{SR}} = (1/T_{\text{SR}}) * (k/n)$$

$$= (1 - P_b)^n * (k/n)$$

where

$$T_{\text{SR}} = 1 \cdot P_{\text{ACK}} + 2 P_{\text{ACK}} (1 - P_{\text{ACK}}) + 3 P_{\text{ACK}} (1 - P_{\text{ACK}})^2$$

$$+ \dots$$

$$= P_{\text{ACK}} \sum_{i=1}^{\infty} i (1 - P_{\text{ACK}})^{i-1}$$

$$= P_{\text{ACK}} / [1 - (1 - P_{\text{ACK}})]^2$$

$$= 1 / (1 - P_b)^n \quad \text{where } P_{\text{ACK}} \approx (1 - P_b)^n$$